Flat Fielding

Flat fielding

- Flat fielding is used to remove Fixed Pattern Noise (FPN) from an image. To apply a flat field, a uniformly illuminated featureless image is divided into the image to be calibrated.
- The flat field is normally averaged from a collection of identical such uniformly illuminated featureless images
- The Flat Fielding process will also remove optical illumination variations, dust motes and other such fixed patterns from the image

FLAT FIELD NOISE SOURCES

READ NOISE (σ_{READ}) (NOISE THAT DOES NOT VARY WITH SIGNAL)

SHOT NOISE (σ_{SHOT})
(RANDOM ARRIVAL OF PHOTONS)

FIXED PATTERN NOISE (σ_{FPN})
(PIXEL TO PIXEL SENSITIVITY VARIATION)

SIGNAL TO NOISE

FLAT FIELD SIGNAL TO NOISE

$$(\frac{S}{N})_{FF} = \frac{4 \times 10^{11} \text{ QE}_{I} \text{ P}_{A} \text{ T}_{C} \text{ T}_{L} \text{ L}_{UX} \text{ t}_{I} (1 + 4 \text{ f}^{2})^{-1}}{(N_{R}^{2} + S_{SN}^{2} \text{ D}_{SN}^{2} + S_{y}^{2} + Q_{N}^{2} + R^{2} + N_{A}^{2} + P_{FPN}^{2} + D_{FPN}^{2} + O_{FPN}^{2})^{1/2}}$$
Photon shot noise
Read noise

IMAGE SIGNAL TO NOISE

(S/N)_I = IMAGE MODULATION / NOISE

$$(\frac{S}{N})_{\rm I} \approx {\rm MTF}_{\rm D} \ {\rm C}_{\rm P} \ (\frac{S}{N})_{\rm FF}$$
 Optimize for highest image S/N

 $MTF_D = DETECTOR MODULATION TRANSFER FUNCTION (MTF_D)$

C_P = INCOMING IMAGE MODULATION OR CONTRAST

PHOTON TRANSFER NOISE REGIMES

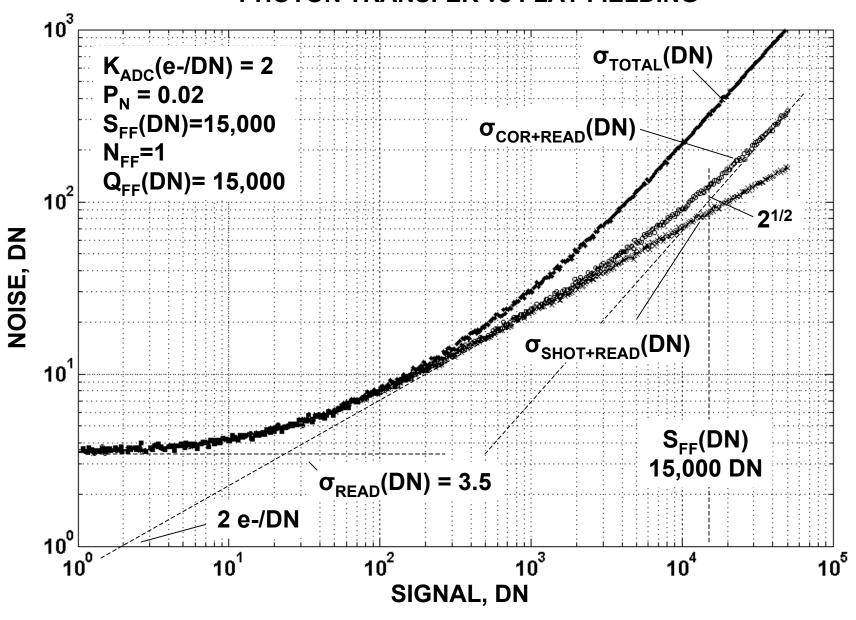
Total noise (e⁻) =
$$(\sigma_{READ}^2 + \sigma_{SHOT}^2 + \sigma_{FPN}^2)^{1/2}$$

$$\sigma_{READ}$$
 = Read noise (rms e⁻)

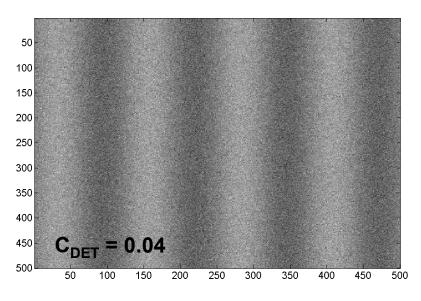
$$\sigma_{SHOT}$$
 = Shot noise (rms e⁻)
= (Signal (e⁻))^{1/2}

All Gaussian Distributed

PHOTON TRANSFER vs FLAT FIELDING

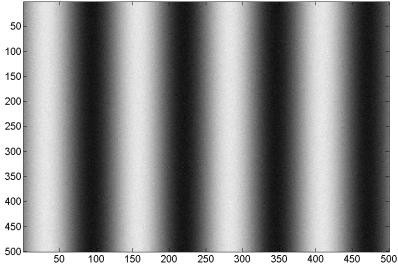


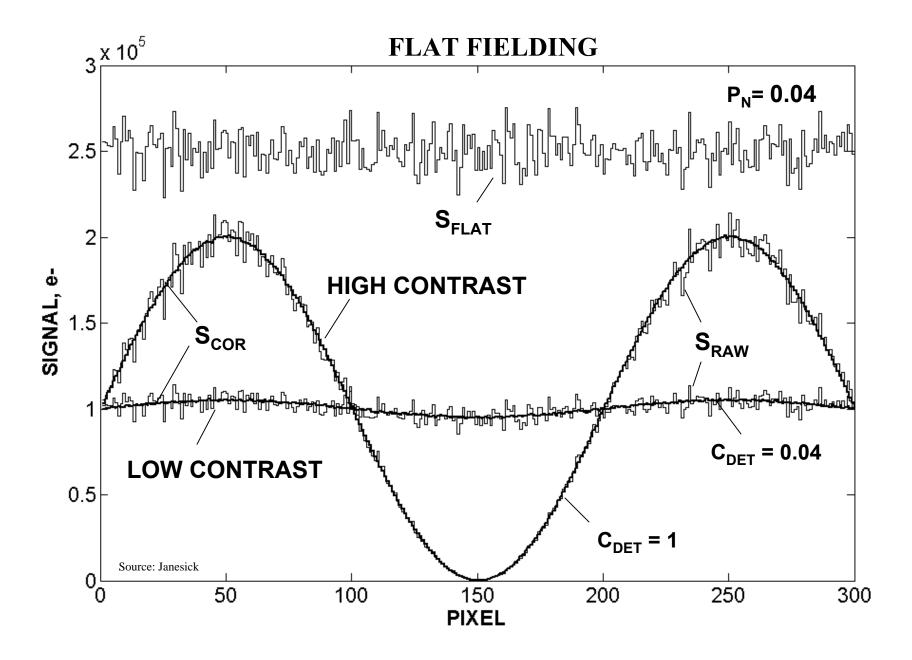
RAW



Source: Janesick

CORRECTED





Resultant noise for the corrected frame. . ..

$$\sigma_{\text{SHOT_COR}}(e-) = (\sigma_{\text{READ}}^2 + (S_{\text{RAW}}(e-)(1 + \frac{S_{\text{RAW}}(e-)}{Q(e-)}))^{1/2}$$

where

$$Q(e-) = S_{FF}(e-)N_{FF}$$

N_{FF} is the number of flat fields averaged

Source: Janesick

